

Model Checking and Games

Part II - Basics of Modelling Reactive Systems

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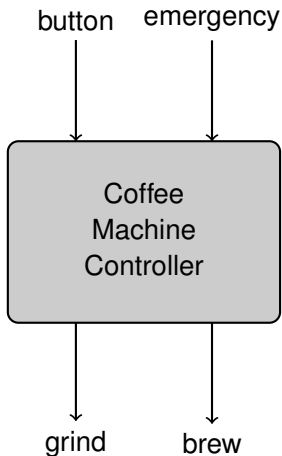
Models of reactive systems

Traces

Reactive systems

- We assume that a system evolves in *steps*
- At every point in time, a reactive system reads its *input* and writes to its *output*
- When we continually observe the input/output of a system, we obtain a *trace* of the system

Reactive systems - example



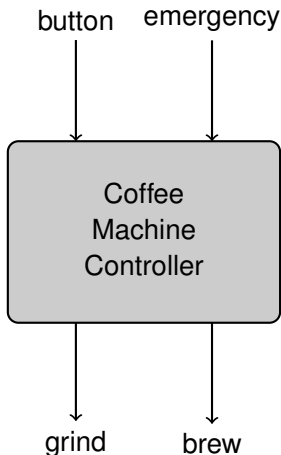
Input/output shape

Here: In every step, the input *bit* has a value and the output *bits* have values, too.

Atomic propositions

- $AP_I = \{\text{button}, \text{emergency}\}$
- $AP_O = \{\text{grind}, \text{brew}\}$

Reactive systems - example



Input/output shape

Here: In every step, the input *bit* has a value and the output *bits* have values, too.

Atomic propositions

- $AP_I = \{\text{button}, \text{emergency}\}$
- $AP_O = \{\text{grind}, \text{brew}\}$

A trace of the system

$$\rho = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 \end{pmatrix} \dots$$

Mealy & Moore machines

Order of the input and output

- **Mealy machine:** in every step of the system's execution, the system first reads the input and then produces the output.
- **Moore machine:** in every step of the system's execution, the system first produces the output and then reads the input.

Mealy machines

Definition

A Mealy machine is a tuple $\mathcal{M} = (S, \Sigma^I, \Sigma^O, \delta, s_0)$ with:

- the set of states S ,
- the input alphabet Σ^I ,
- the output alphabet Σ^O ,
- the transition function $\delta : S \times \Sigma^I \rightarrow S \times \Sigma^O$, and
- the initial state $s_0 \in S$.

Traces & runs

A *trace* of \mathcal{M} is an infinite sequence $\rho = (\rho_0^O, \rho_0^I)(\rho_1^O, \rho_1^I) \dots \in (\Sigma^I \times \Sigma^O)^\omega$ such that there exists a corresponding *run* of \mathcal{M} of the form $\pi = \pi_0 \pi_1 \dots \in S^\omega$ with $(\pi_{i+1}, \rho_i^O) = \delta(\pi_i, \rho_i^I)$ for for all $i \in \mathbb{N}$ and $\pi_0 = s_0$.



On notation

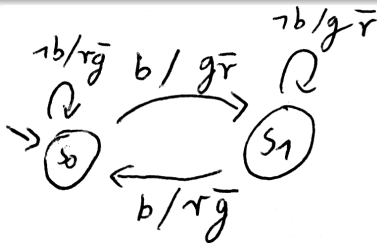
A note on alphabets

In most examples, we will have $\Sigma^I = 2^{AP^I}$ and $\Sigma^O = 2^{AP^O}$ for some sets of *atomic propositions* AP^I and AP^O .

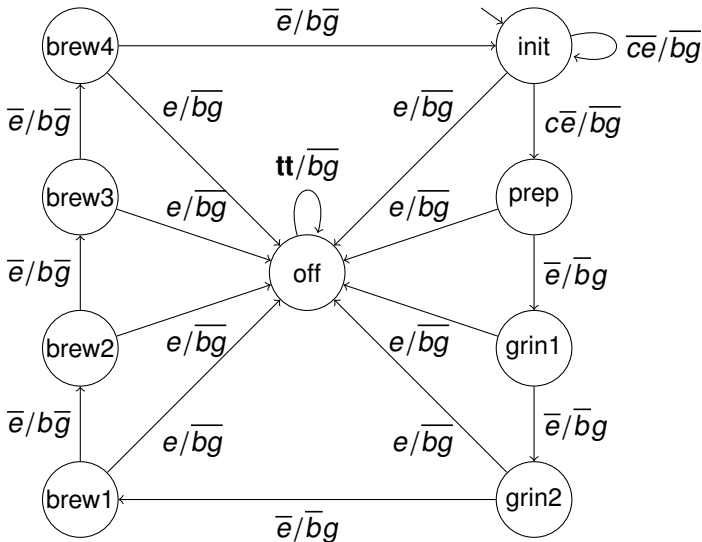
The definition of Mealy machines does not require this, however.

Graphical notation for Mealy machines

Example: $\mathcal{M} = (S, \Sigma^I, \Sigma^O, \delta, s_0)$ with $S = \{s_0, s_1\}$, $\Sigma^I = 2^{\{b\}}$, $\Sigma^O = 2^{\{r, g\}}$, $\delta(s_0, \emptyset) = (s_0, \{r\})$, $\delta(s_0, \{b\}) = (s_1, \{g\})$, $\delta(s_1, \emptyset) = (s_1, \{g\})$, $\delta(s_1, \{b\}) = (s_0, \{r\})$.



Example: Coffee machine





Moore machines

Definition

A Moore machine is a tuple $\mathcal{M} = (S, \Sigma^I, \Sigma^O, \delta, L, s_0)$ with:

- the set of states S ,
- the input alphabet Σ^I ,
- the output alphabet Σ^O ,
- the labeling function $L : S \rightarrow \Sigma^O$,
- the transition function $\delta : S \times \Sigma^I \rightarrow S$, and
- the initial state $s_0 \in S$.

Traces & runs

A *trace* of \mathcal{M} is an infinite sequence $\rho = (\rho_0^O, \rho_0^I)(\rho_1^O, \rho_1^I) \dots \in (\Sigma^I \times \Sigma^O)^\omega$ such that there exists a corresponding *run* of \mathcal{M} of the form $\pi = \pi_0 \pi_1 \dots \in S^\omega$ with $\pi_{i+1} = \delta(\pi_i, \rho_i^I)$ and $L(\pi_i) = \rho_i^O$ for all $i \in \mathbb{N}$.

Mealy vs. Moore machines (1)

Differences

- Mealy machines read the input *before* selecting the next output
- Moore machines read the input *after* selecting the next output

Mealy \rightarrow Moore translation

Translation Moore \rightarrow Mealy

Given a Moore machine $\mathcal{M} = (S, \Sigma^I, \Sigma^O, \delta, L, s_0)$, we define its corresponding translation to a Mealy machine $\mathcal{M}' = (S, \Sigma^I, \Sigma^O, \delta', s_0)$ with:

- $\delta'(s, i) = (\delta(s, i), L(s))$ for all $s \in S, i \in \Sigma^I$

Lemma

Claim: \mathcal{M} and \mathcal{M}' induce the same set of traces.

Proof: \Rightarrow Let $\rho = (\rho_0^O, \rho_0^I)(\rho_1^O, \rho_1^I) \dots \in$ be a trace of \mathcal{M} and $\pi = \pi_0 \pi_1 \dots$ be the corresponding run. So we have that for every $i \in \mathbb{N}$, by definition, $\pi_{i+1} = \delta(\pi_i, \rho_i^I)$ and $L(\pi_i) = \rho_i^O$ for all $i \in \mathbb{N}$. By the definition of δ' , we also have $\delta'(\pi_i, \rho_i^I) = (\pi_{i+1}, \rho_i^O)$ for all $i \in \mathbb{N}$. Since $\pi_0 = s_0$ (by assumption), this means that ρ is also a trace of \mathcal{M}' .

\Leftarrow : Analogous

Less structured models: Transition systems



Definition

A *transition system* is a tuple (S, S_0, T) with:

- a set of states S ,
- a set of initial states S_0 , and
- a set of transitions $T \subseteq S \times S$.

Transition systems (2)

Definition

Given a transition system $\mathcal{T} = (S, S_0, T)$, we say that

- a sequence $\pi = \pi_0\pi_1 \dots \in S^\omega$ is an *infinite run* of \mathcal{T} if we have $\pi_0 \in S_0$ and for every $i \in \mathbb{N}$, we have $(\pi_i, \pi_{i+1}) \in T$, and
- a sequence $\pi = \pi_0\pi_1 \dots \pi_n \in S^*$ is a *finite run* of \mathcal{T} if we have $\pi_0 \in S_0$ and for every $i \in \{0, \dots, n-1\}$, we have $(\pi_i, \pi_{i+1}) \in T$.

Transition systems vs. Mealy and Moore machines

Differences

- Transition systems have less structure: No explicit input or output, no labels.
- Transition systems have *non-determinism*: no single initial state, system can behave arbitrarily.

Kripke structures: *Labeled transition systems*

Definition

A *Kripke structure* is a tuple (S, S_0, T, AP, L) with:

- a set of states S ,
- a set of initial states S_0 , and
- a set of transitions $T \subseteq S \times S$.
- a set of *propositions* AP , and
- a labelling function $L : S \rightarrow 2^{AP}$.

Traces of Kripke structures



Definition (infinite trace)

If $\pi = \pi_0\pi_1 \dots \in S^\omega$ is an *infinite run* of \mathcal{T} , then we call $\rho = L(\pi_0)L(\pi_1) \dots$ an *infinite trace* of \mathcal{T} .

Definition (finite trace)

If $\pi = \pi_0\pi_1 \dots \pi_n \in S^*$ is a *finite run* of \mathcal{T} , then we call $\rho = L(\pi_0)L(\pi_1) \dots L(\pi_n)$ a *finite trace* of \mathcal{T} .

Comparison: LTS vs Mealy & Moore machines

Comparison

| Aspect | Mealy / Moore Machines | Labeled Transition systems |
|----------------------------------|-------------------------------|-----------------------------------|
| Input & Output | Clearly separated | No separation |
| Determinism | Yes | No |
| Time | Discrete time steps | No concrete notion of time |
| Ability to abstract from details | No | Yes |
| Non-binary alphabets | Yes | No |

Use of Kripke structures

They are a good model for verifying systems to be correct!

If we want to analyze for whether a system works correctly, they are a suitable model.

If we capture the desired behavior of the system as a *set of (allowed) traces*, then we can check if the traces of the model are all contained in them.

Use of Kripke structures

They are a good model for verifying systems to be correct!

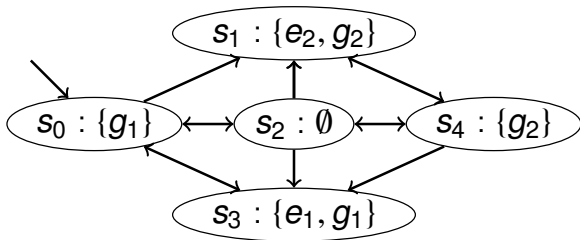
If we want to analyze for whether a system works correctly, they are a suitable model.

If we capture the desired behavior of the system as a *set of (allowed) traces*, then we can check if the traces of the model are all contained in them.

But beware!

The LTS must capture *all* possible executions of the system for this to work!

Revisiting the traffic light with an ambulance override



Question: Are there traces induced by this Kripke structure on which the second green light (g_2) is never lit?



Translation from Mealy/Moore machines to Kripke structures

Definition by example of Moore machines

Given a Moore machine $\mathcal{M} = (S, \Sigma^I, \Sigma^O, \delta, L, s_0)$ with $\Sigma^I = 2^{AP^I}$ and $\Sigma^O = 2^{AP^O}$, we define the *corresponding* Kripke structure $\mathcal{K} = (S', S'_0, T', AP, L')$ with:

- $S' = S \times \Sigma^I \uplus \{\cdot\}$
- $S'_0 = \{\cdot\}$
- $AP = AP^I \uplus AP^O$
- $T = \{(\cdot, (s, i)) \mid i \subseteq 2^{AP^I}, s \in S_0\} \cup \{((s, i), (s', i')) \mid (s, i), (s', i') \in S \times \Sigma^I, (s, i, s') \in \delta\}$
- For all $(s, i) \in S \times \Sigma^I$, $L'((s, i)) = L(s) \cup i$
- $L'(\cdot) = \emptyset$

Consequence

Consequence

If we want to reason about the set of possible traces of a Mealy or Moore machine (e.g., for verifying that the Mealy or Moore machine has some desired properties), we can do so on the corresponding Kripke structure.

Side-note

...but non-binary alphabets may require some care.

Let's look at circuits

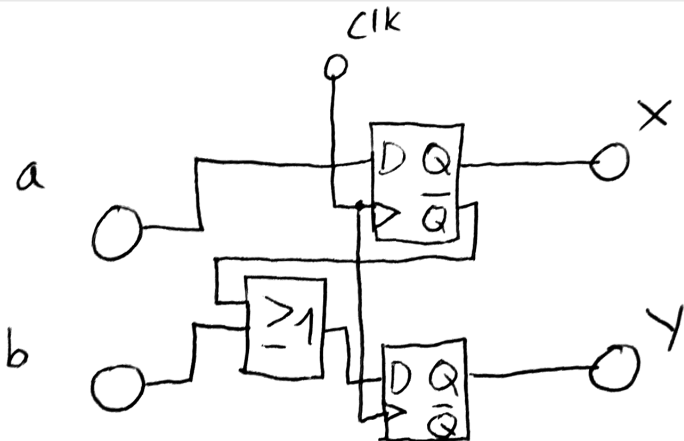
Modelling the behavior of a circuit as a Kripke structure

We can also analyze the behavior of a circuit

Let's look at circuits

Modelling the behavior of a circuit as a Kripke structure

We can also analyze the behavior of a circuit

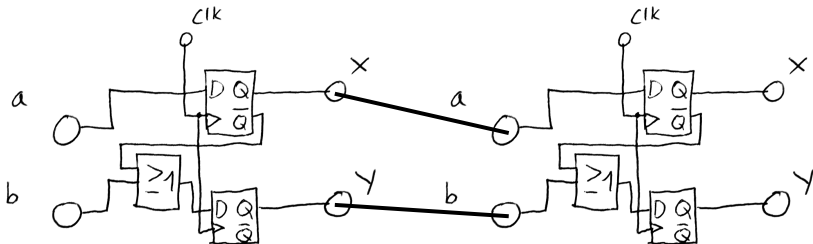


Large circuits

Observation

The Kripke structures can grow quite large in this process. For larger circuits, we need some **structured way** to compose the parts:

Example:

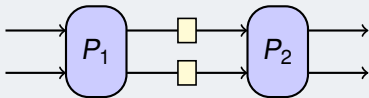


Synchronous communication between processes

Possibility 1: Synchronous composition in the same time step



Possibility 2: Synchronous composition with delay



Synchronous composition (delayed version)



Definition

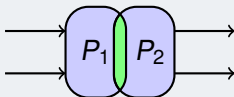
Let $\mathcal{K}^1 = (S^1, S_0^1, T^1, AP^1, L^1)$ and $\mathcal{K}^2 = (S^2, S_0^2, T^2, AP^2, L^2)$ be Kripke structures.

We define the *synchronous product (with delay)* of \mathcal{K}^1 and \mathcal{K}^2 as the Kripke structure $\mathcal{K}^P = (S^P, S_0^P, T^P, AP^P, L^P)$ with:

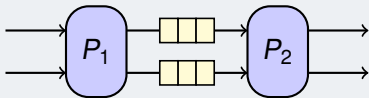
- $S^P = S^1 \times S^2$
- $S_0^P = S_0^1 \times S_0^2$
- $AP^P = \{p^1 \mid p \in AP^1\} \cup \{p^2 \mid p \in AP^2\}$
- $L((s^1, s^2)) = \{p^1 \mid p \in L^1(s^1)\} \cup \{p^2 \mid p \in L^2(s^2)\}$
- $T^P = \{((s^1, s^2), (s'^1, s'^2)) \subseteq S^P \mid L^2(s'^2) \cap AP^1 \cap AP^2 = L^1(s^1) \cap AP^1 \cap AP^2\}.$

Asynchronous composition between processes

Possibility 3: Shared variables



Possibility 4: Asynchronous composition with channels





Towards asynchronous composition: Modelling software as Kripke structures

Example program (Peterson's Mutex algorithm, part 1)

```
bool flag0 = false;
bool flag1 = false;
bool turn = false;
while (true) {
    flag0 = true;
    turn = false;
    while (flag1 == true && turn == false) {
        skip;
    }
    while (havoc) {
        skip;
    }
    flag0 = false;
    while (havoc) {
        skip;
    }
}
```



Towards asynchronous composition: Modelling software as Kripke structures

Example program (Peterson's Mutex algorithm, part 1)

```
    bool flag0 = false;
    bool flag1 = false;
    bool turn = false;
10: while (true) {
11:     flag0 = true;
12:     turn = false;
13:     while (flag1 == true && turn == false) {
14:         skip;
15:     }
16:     while (havoc) {
17:         skip;
18:     }
19:     flag0 = false;
20:     while (havoc) {
21:         skip;
22:     }
}
```



Towards asynchronous composition: Modelling software as Kripke structures

Example program (Peterson's Mutex algorithm, all parts)

```
bool flag0 = false;
bool flag1 = false;
bool turn = false;

10: while (true) {
11:     flag0 = true;
12:     turn = false;
13:     while (flag1 == true &&
14:         turn == false) {
15:         skip;
16:     }
17:     while (havoc) {
18:         skip;
19:     }
    flag0 = false;
    while (havoc) {
        skip;
    }
}

|| m0: while (true) {
|| m1:     flag1 = true;
|| m2:     turn = true;
|| m3:     while (flag0 == true &&
|| m4:         turn == true) {
|| m5:         skip;
|| m6:     }
|| m7:     while (havoc) {
|| m8:         skip;
|| m9:     }
|| m10: flag1 = false;
|| m11: while (havoc) {
|| m12:     skip;
|| m13: }
|| }
```


Asynchronous composition



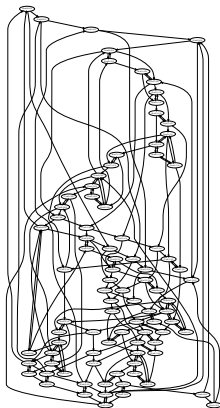
Definition

Let $\mathcal{K}^1 = (S^1, S_0^1, T^1, AP^1, L^1)$ and $\mathcal{K}^2 = (S^2, S_0^2, T^2, AP^2, L^2)$ be Kripke structures such that $S^1 = V \times M^1$ and $S^2 = V \times M^2$.

We define the *asynchronous product* of \mathcal{K}^1 and \mathcal{K}^2 as the Kripke structure $\mathcal{K}^P = (S^P, S_0^P, T^P, AP^P, L^P)$ with:

- $S^P = M^1 \times M^2 \times V$
- $S_0^P = \{(m^1, m^2, v) \in S^P \mid (m^1, v) \in S_0^1, (m^2, v) \in S_0^2\}$
- $AP^P = AP^1 \cup AP^2$
- $L((m^1, m^2, v)) = L^1((m^1, v)) \cup L^2((m^2, v))$
- $T^P = \{((m^1, m^2, v), (m'^1, m^2, v')) \mid ((m^1, v), (m'^1, v')) \in T^1\} \cup \{((m^1, m^2, v), (m^1, m'^2, v')) \mid ((m^2, v), (m'^2, v')) \in T^2\}$

Complete product





Simplified example

Simplified program (Peterson's Mutex algorithm, all parts)

```
bool flag0 = false;
bool flag1 = false;
bool turn = false;

10: while (true) {           || m0: while (true) {
    flag0 = true;           ||     flag1 = true;
11:   turn = false;         || m1:   turn = true;
12:   while (flag1 == true && || m2:   while (flag0 == true &&
        turn == false) {   ||       turn == true) {
        skip;              ||       skip;
    }                      ||   }
13:   while (havoc) {       || m3:   while (havoc) {
        skip;              ||       skip;
    }                      ||   }
14:   flag0 = false;        || m4:   flag1 = false;
15:   while (havoc) {       || m5:   while (havoc) {
        skip;              ||       skip;
    }                      ||   }
}                          || }
```


Discussion

Kripke structures & transition systems

- Give an account of what states in a system can be reached
- They can be labeled or not depending on what we want to analyze about them:
 - Are certain states reachable?
 - What traces does the Kripke structure induce?
- We already saw the **state space explosion** problem: even for small circuits/programs/models, the number of states can become **huge**!

The model checker spin

Some facts

- Developed by Gerard Holzmann
- Uses the specification language Promela (for “Process meta language”)
- Runs under Unix/Linux, compiles models into executable code for enumerating the states in a transition system

Official Website: <http://spinroot.com>

Getting spin to run



Local “Installation” (using the RZ application server):

```
ssh -Y username@cloud-249.rz.tu-clausthal.de
git clone https://github.com/nimble-code/Spin.git
cd Spin
make
cd ..
```

Using the GUI after logging in (with `ssh -Y`):

```
bash
export PATH=$PATH:~/Spin/Src
~/Spin/optional_gui/ispin.tcl
```

Unter Windows, you may want want to try MobaXTerm or a similar tool instead of `ssh` (or start from a Linux virtual machine).

Summary / List of Concepts

- Synchronous reactive systems, Mealy and Moore machines
- Labeled transition systems & Kripke structures
- Traces of Mealy machines, Moore machine, and Kripke structures
- Programs as models
- Composition of Kripke structures: synchronous (delayed) and asynchronous (with shared variables)
- Model checker spin



References I